# Infinitely many solutions for two noncooperative $p(x)$-Laplacian elliptic systems * 

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#### Abstract

The author deals with two noncooperative elliptic systems involving $p(x)$ Laplacian in a smooth bounded domain and in $\mathbb{R}^{N}$ respectively. With some symmetry assumptions and growth conditions on nonlinearities, the existences of infinitely many solutions are obtained by using a limit index theory developed by Li (Nonlinear Anal.: TMA, 25(1995) 1371) in variable exponent Sobolev spaces.


Keywords: variable exponent Sobolev spaces; noncooperative elliptic systems; limit index theory; $p(x)$-Laplacian

Mathematics Subject Classification(2000): 35J50; 35B38

## 1 Introduction

The theory of variable exponent Lebesgue and Sobolev spaces has been developed by several researchers in recent years. These spaces are natural generalization of the classical Lebesgue space $L^{p}(\Omega)$ and the Sobolev space $W^{k, p}(\Omega)$. Although the study of these spaces can go back to [21] and [20] as special cases of Musielak-Orlicz spaces, the first paper systematically investing these spaces appeared in 1991 by Kováčik and Rákosník [17]. These spaces have been independently rediscovered by several researchers based on different background. We refer to Samko [24], Fan and Zhao [12], Acerbi and Mingione [1]. We also refer to three survey papers of these areas by Harjulehto and Hästö [15], by Diening, Hästö and Nekvinda [4] and by Samko [25]. Many applications have been found such as variational integrals with nonstandard growth conditions in nonlinear elasticity theory by Zhikov [31], models in electrorheological fluids by Růžička [23], and models in image restoration by Chen, Levine and Rao [3].

[^0]In this paper, we consider the following two noncooperative elliptic systems involving $p(x)$-Laplacian in a smooth bounded domain $\Omega$ and in $\mathbb{R}^{N}$ respectively:

$$
\begin{gather*}
\left\{\begin{aligned}
\triangle_{p(x)} u=F_{s}(x, u, v) & \text { in } \Omega, \\
-\triangle_{p(x)} v & =F_{t}(x, u, v) \\
\left.u\right|_{\partial \Omega}=0, & \text { in }\left.\Omega\right|_{\partial \Omega}=0 ;
\end{aligned}\right.  \tag{1.1}\\
\left\{\begin{aligned}
\triangle_{p(x)} u-|u|^{p(x)-2} u=G_{s}(|x|, u, v) & \text { in } \mathbb{R}^{N}, \\
-\triangle_{p(x)} v+|v|^{p(x)-2} v=G_{t}(|x|, u, v) & \text { in } \mathbb{R}^{N} ;
\end{aligned}\right. \tag{1.2}
\end{gather*}
$$

where $\triangle_{p(x)} u:=\operatorname{div}\left(|\nabla u|^{p(x)-2} \nabla u\right)$ is called the $p(x)$-Laplacian, $F(x, s, t) \in C^{1}(\bar{\Omega} \times$ $\left.\mathbb{R}^{2}, \mathbb{R}\right), G(r, s, t) \in C^{1}\left([0, \infty) \times \mathbb{R}^{2}, \mathbb{R}\right), F_{s}=\frac{\partial F}{\partial s}$ and similar to $F_{t}, G_{s}, G_{t}$.

Many results about $p(x)$-Laplacian equations with Dirichlet boundary conditions ([11, 5, 6]), Neumann boundary conditions ([19]) and in $\mathbb{R}^{N}$ cases ([8, [28]) have been obtained by variational approach and sub-supersolution method. Acerbi and Mingione [1] have obtained the local $C^{1, \alpha}$ regularity of minimizers of the integral functional with $p(x)$-growth conditions under the assumption that $p(x)$ is Hölder continuous. The global regularity results have also been obtained by Fan [7]. There are some results about elliptic systems. Hamidi [14] considered the following system

$$
\begin{cases}-\triangle_{p(x)} u=F_{s}(x, u, v) & \text { in } \Omega,  \tag{1.3}\\ -\triangle_{q(x)} v=F_{t}(x, u, v) & \text { in } \Omega \\ \left.u\right|_{\partial \Omega}=0, & \left.v\right|_{\partial \Omega}=0\end{cases}
$$

and obtained the existence of solution since the integral functional of (1.3) is coercive and satisfies mountain pass geometry under some assumptions on $F$. The author also gave the multiplicity results by using the Fountain theorem when some symmetry condition on $F$ is assumed. Zhang [29] considered the system

$$
\begin{cases}-\triangle_{p(x)} u=f(v) & \text { in } \Omega  \tag{1.4}\\ -\triangle_{p(x)} v=g(u) & \text { in } \Omega \\ \left.u\right|_{\partial \Omega}=0,\left.\quad v\right|_{\partial \Omega}=0 & \end{cases}
$$

on a bounded radial symmetric domain with $p(x)$ radial symmetric, and proved the existence of a positive solution under some assumptions by sub-supersolution method. He also considered the existence of solutions for weighted $p(r)$-Laplacian system boundary value problems via Leray-Schauder degree in [30].

The main difficulties we meet here are that the corresponding integral functionals of (1.1) and (1.2) are strongly indefinite. In addition to the nonlinearity of $p(x)$ Laplacian operator, we also lose a compact embedding theorem in $\mathbb{R}^{N}$ case. Thanks to a limit index theory developed by Li [18] and the principle of symmetric criticality
due to Palais 22 in $\mathbb{R}^{N}$ case, we can obtain the existence of infinitely many solutions of problems 1.1 and 1.2 in the spaces $W_{0}^{1, p(x)}(\Omega)$ and $W^{1, p(x)}\left(\mathbb{R}^{N}\right)$ respectively under some nature assumptions on the nonlinearities.

Let us denote by $c$ or $c_{i}$ some generic positive constants which may be different throughout the paper.

Below are the assumptions.
(P1) $p(x) \in C(\bar{\Omega})$ and $1<\inf _{\Omega} p(x):=p_{-} \leq p_{+}:=\sup _{\Omega} p(x)<\infty$.
(P2) $p(x)=p(|x|):=p(r) \in C^{0,1}\left(\mathbb{R}^{N}\right)$ with $1<\inf _{\mathbb{R}^{N}} p(x):=p_{-} \leq p_{+}:=$ $\sup _{\mathbb{R}^{N}} p(x)<N$.
(F1) $F \in C^{1}\left(\bar{\Omega} \times \mathbb{R}^{2}, \mathbb{R}\right)$.
(F2) $\left|F_{s}(x, s, t)\right|+\left|F_{t}(x, s, t)\right| \leq c_{1}+c_{2}\left(|s|^{r(x)-1}+|t|^{r(x)-1}\right)$ where $r(x) \in C(\bar{\Omega})$, $2 \leq r(x)<p^{*}(x)$.

$$
p^{*}(x):= \begin{cases}\frac{N p(x)}{(N-p(x))}, & \text { if } p(x)<N, \\ \infty, & \text { if } p(x) \geq N\end{cases}
$$

(F3) $\exists M>0$ and $\mu>p_{+}$such that

$$
0<\mu F(x, s, t) \leq s F_{s}(x, s, t)+t F_{t}(x, s, t)
$$

for all $(x, s, t) \in \bar{\Omega} \times \mathbb{R}^{2}$ with $s^{2}+t^{2} \geq M^{2}$. In this case, $F(x, s, t) \geq c_{1}\left(|s|^{\mu}+|t|^{\mu}\right)-c_{2}$. (F4) $s F_{s}(x, s, t) \geq 0$, for all $(x, s, t) \in \bar{\Omega} \times \mathbb{R}^{2}$.
(F5) $F(x,-s,-t)=F(x, s, t)$, for all $(x, s, t) \in \bar{\Omega} \times \mathbb{R}^{2}$.
(G1) $G \in C^{1}\left([0, \infty) \times \mathbb{R}^{2}, \mathbb{R}\right)$.
(G2) For some $p(x) \ll q(x) \ll p^{*}(x)$,

$$
\left|G_{s}(|x|, s, t)\right|+\left|G_{t}(|x|, s, t)\right| \leq c_{1}\left(|s|^{p(x)-1}+|t|^{p(x)-1}\right)+c_{2}\left(|s|^{q(x)-1}+|t|^{q(x)-1}\right)
$$

The symbol $\alpha(x) \ll \beta(x)$ means $\inf _{\bar{\Omega}}(\beta(x)-\alpha(x))>0$.
(G3) $\exists M>0$ and $\mu>p_{+}$such that

$$
0<\mu G(r, s, t) \leq s G_{s}(r, s, t)+t G_{t}(r, s, t)
$$

for all $(r, s, t) \in[0, \infty) \times \mathbb{R}^{2}$ with $s^{2}+t^{2} \geq M^{2}$.
(G4) $\left|G_{s}(|x|, s, t)\right|+\left|G_{t}(|x|, s, t)\right|=o\left(|s|^{\mid p(x)-1}\right)+o\left(|t|^{p(x)-1}\right)$ uniformly on $\mathbb{R}^{N}$ as $s^{2}+t^{2} \rightarrow 0$.
(G5) $s G_{s}(r, s, t) \geq 0$, for all $(r, s, t) \in[0, \infty) \times \mathbb{R}^{2}$.
(G6) $G(r,-s,-t)=G(r, s, t)$, for all $(r, s, t) \in[0, \infty) \times \mathbb{R}^{2}$.
The following are the main results.
Theorem 1.1 Suppose that (P1) and (F1)-(F5) are satisfied. Let $\Phi(u, v)$ be the integral functional of (1.1). Then problem (1.1) possesses a sequence of weak solutions $\left\{ \pm\left(u_{n}, v_{n}\right)\right\}$ in $W_{0}^{1, p(x)}(\Omega) \times W_{0}^{1, p(x)}(\Omega)$ such that $\Phi\left(u_{n}, v_{n}\right) \rightarrow+\infty$ as $n \rightarrow \infty$.

Theorem 1.2 Suppose that (P2) and (G1)-(G6) are satisfied. Let $\Psi(u, v)$ be the integral functional of (1.2). Then problem (1.2) possesses a sequence of radial weak solutions $\left\{ \pm\left(u_{n}, v_{n}\right)\right\}$ in $W^{1, p(x)}\left(\mathbb{R}^{N}\right) \times W^{1, p(x)}\left(\mathbb{R}^{N}\right)$ such that $\Psi\left(u_{n}, v_{n}\right) \rightarrow+\infty$ as $n \rightarrow \infty$. In addition, if $N=4$ or $N \geq 6$, the problem (1.2) possesses infinitely many nonradial weak solutions.

Remark 1.3 The definitions of weak solution of (1.1) and (1.2) are given in Definition 3.1 and Definition 4.1 respectively.

Remark 1.4 When $p(x) \equiv p$ (a constant), the corresponding results have been obtained by Li in [18] and by Huang and Li in [16]. The aim of the present paper is to generalize their results to general cases.

The paper is organized as follows. In Section 2.1 we do some preliminaries of the space $W_{0}^{1, p(x)}(\Omega)$ and $W^{1, p(x)}\left(\mathbb{R}^{N}\right)$, review some basic properties of $p(x)$-Laplacian operator. In Section 2.2 we recall a limit index theory due to Li. In Section 3, we prove Theorem 1.1. In Section 4, we prove Theorem 1.2 .

## 2 Preliminaries

### 2.1 Variable exponent Sobolev spaces and $p(x)$-Laplacian operator

Let $\Omega$ be an open subset of $\mathbb{R}^{N}$. In this subsection, without further assumption, $\Omega$ could be $\mathbb{R}^{N}$. On the basic properties of the space $W^{1, p(x)}(\Omega)$ we refer to [17, 12]. In the following we display some facts which we will use later.

Denote by $S(\Omega)$ the set of all measurable real functions defined on $\Omega$, and elements in $S(\Omega)$ that equal to each other almost everywhere are considered as one element. Denote $L_{+}^{\infty}(\Omega)=\left\{p \in L^{\infty}(\Omega): \operatorname{ess}_{\inf }^{\Omega} p(x):=p_{-} \geq 1\right\}$.

For $p \in L_{+}^{\infty}(\Omega)$, define

$$
L^{p(x)}(\Omega)=\left\{u \in S(\Omega): \int_{\Omega}|u|^{p(x)} \mathrm{d} x<\infty\right\},
$$

with the norm

$$
|u|_{L^{p(x)}(\Omega}=|u|_{p(x)}=\inf \left\{\lambda>0: \int_{\Omega}|u / \lambda|^{p(x)} \mathrm{d} x \leq 1\right\}
$$

and define

$$
W^{1, p(x)}(\Omega)=\left\{u \in L^{p(x)}(\Omega):|\nabla u| \in L^{p(x)}(\Omega)\right\}
$$

with the norm

$$
\|u\|_{W^{1, p(x)}(\Omega)}=|u|_{L^{p(x)}(\Omega)}+|\nabla u|_{L^{p(x)}(\Omega)} .
$$

We denote by $W_{0}^{1, p(x)}(\Omega)$ the closure of $C_{0}^{\infty}(\Omega)$ in $W^{1, p(x)}(\Omega)$. Define

$$
W_{r}^{1, p(x)}\left(\mathbb{R}^{N}\right)=\left\{u \in W^{1, p(x)}\left(\mathbb{R}^{N}\right): \mathrm{u} \text { is radially symmetric }\right\} .
$$

Hereafter, we always assume that $p(x)$ is continuous and $p_{-}>1$.
Proposition 2.1 ( $17,[12]$ ) The spaces $L^{p(x)}(\Omega), W^{1, p(x)}(\Omega), W_{0}^{1, p(x)}(\Omega)$ and $W_{r}^{1, p(x)}\left(\mathbb{R}^{N}\right)$ all are separable and reflexive Banach spaces.

Proposition 2.2 ( $\sqrt[17]{ }, ~[12, ~[9])$ The conjugate space of $L^{p(x)}(\Omega)$ is $L^{p^{\circ}(x)}(\Omega)$, where $\frac{1}{p(x)}+\frac{1}{p^{o}(x)}=1$. For any $u \in L^{p(x)}(\Omega)$ and $v \in L^{p^{o}(x)}(\Omega)$, the Hölder inequality holds:

$$
\begin{equation*}
\int_{\Omega}|u v| \mathrm{d} x \leq 2|u|_{p(x)}|v|_{p^{o}(x)} . \tag{2.1}
\end{equation*}
$$

Remark 2.3 In the right of (2.1), the constant 2 is suitable, but not the best. The best constant is given in [9] denoted by $d_{\left(p_{-}, p_{+}\right)}$which only depends on $p_{-}$and $p_{+}$ when $p(x)$ is given and $d_{\left(p_{-}, p_{+}\right)}$is smaller than $\frac{1}{p_{-}}+\frac{1}{p_{+}}$.

Proposition 2.4 (12] Theorem 2.7) Suppose that $\Omega$ is a bounded domain. In $W_{0}^{1, p(x)}(\Omega)$ the Poincaré inequality holds, that is, there exists a positive constant c such that

$$
|u|_{p(x)} \leq c|\nabla u|_{p(x)}, \quad \text { for all } u \in W_{0}^{1, p(x)}(\Omega)
$$

So $|\nabla u|_{p(x)}$ is an equivalent norm in $W_{0}^{1, p(x)}(\Omega)$.
Remark 2.5 When $\Omega$ is a bounded domain, we denote by $\|u\|:=|\nabla u|_{p(x)}$ as the equivalent norm in $W_{0}^{1, p(x)}(\Omega)$ in Section 3. In Section 4 we will use the following equivalent norm on $W^{1, p(x)}\left(\mathbb{R}^{N}\right)$ also with the symbol $\|u\|$ :

$$
\begin{equation*}
\|u\|:=\inf \left\{\lambda>0: \int_{\Omega}\left(|\nabla u|^{p(x)}+|u|^{p(x)}\right) / \lambda^{p(x)} \mathrm{d} x \leq 1\right\} . \tag{2.2}
\end{equation*}
$$

Proposition 2.6 ([12] Theorem 1.3) Set $\rho(u)=\int_{\Omega}|u(x)|^{p(x)} \mathrm{d} x$. For $u$, $u_{k}$ in the space $L^{p(x)}(\Omega)$, we have
(1) $|u|_{p(x)}<1(=1 ;>1) \Longleftrightarrow \rho(u)<1(=1 ;>1)$;
(2) $|u|_{p(x)}>1 \Rightarrow|u|_{p(x)}^{p^{-}} \leq \rho(u) \leq|u|_{p(x)}^{p^{+}} ;|u|_{p(x)}<1 \Rightarrow|u|_{p(x)}^{p^{+}} \leq \rho(u) \leq|u|_{p(x)}^{p^{-}}$;
(3) $\lim _{k \rightarrow \infty}\left|u_{k}\right|_{p(x)}=0(=\infty) \Longleftrightarrow \lim _{k \rightarrow \infty} \rho\left(u_{k}\right)=0(=\infty)$.

Proposition 2.7 Let $X$ be the space $W_{0}^{1, p(x)}(\Omega)$ or the space $W^{1, p(x)}\left(\mathbb{R}^{N}\right)$ with the norm $\|\cdot\|$ as Remark 2.5. Set $I(u)=\int_{\Omega}|\nabla u(x)|^{p(x)} \mathrm{d} x$ when $\Omega$ is bounded or $I(u)=\int_{\mathbb{R}^{N}}\left(|\nabla u(x)|^{p(x)}+|u(x)|^{p(x)}\right) \mathrm{d} x$ in the $\mathbb{R}^{N}$ case respectively. If $u, u_{k} \in X$ then the similar conclusions of Proposition 2.6 hold for $\|\cdot\|$ and $I(\cdot)$.

Proposition 2.8 ( $17,[12])$ Let $F: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ satisfies Carathéodory conditions, and

$$
|F(x, t)| \leq a(x)+b|t| \frac{p_{1}(x)}{p_{2}(x)}, \quad \text { for all }(x, t) \in \Omega \times \mathbb{R}
$$

where $a \in L^{p_{2}(x)}(\Omega), b$ is a positive constant, $p_{1}, p_{2} \in L_{+}^{\infty}(\Omega)$. Denote by $N_{F}$ the Nemytsky operator defined by $F$, i.e.

$$
\left(N_{F}(u)\right)(x)=F(x, u(x)),
$$

then $N_{F}: L^{p_{1}(x)}(\Omega) \rightarrow L^{p_{2}(x)}(\Omega)$ is a continuous and bounded map.
Proposition 2.9 ([10] Theorem 1.1.) If $p: \Omega \rightarrow \mathbb{R}$ is Lipschitz continuous and $p_{+}<N$, then for $q \in L_{+}^{\infty}(\Omega)$ with $p(x) \leq q(x) \leq p^{*}(x)$, there is a continuous embedding $W^{1, p(x)}(\Omega) \hookrightarrow L^{q(x)}(\Omega)$.

Proposition 2.10 ([5] Proposition 2.4.) Assume that the boundary of $\Omega$ possesses the cone property and $p \in C(\bar{\Omega})$. If $q \in C(\bar{\Omega})$ and $1 \leq q(x)<p^{*}(x)$ for $x \in \bar{\Omega}$, then there is a compact embedding $W^{1, p(x)}(\Omega) \hookrightarrow L^{q(x)}(\Omega)$.

Proposition 2.11 (13] Theorem 3.1.) Suppose that $p: \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a uniformly continuous and radially symmetric function satisfying $1<p_{-} \leq p_{+}<N$. Then, for any measurable function $q: \mathbb{R}^{N} \rightarrow \mathbb{R}$ with

$$
p(x) \ll q(x) \ll p^{*}(x), \quad \text { for all } x \in \mathbb{R}^{N},
$$

there is a compact embedding

$$
W_{r}^{1, p(x)}\left(\mathbb{R}^{N}\right) \hookrightarrow L^{q(x)}\left(\mathbb{R}^{N}\right) .
$$

Definition 2.12 On the space $L^{p(x)}(\Omega) \cap L^{q(x)}(\Omega)$, we define the norm $|u|_{p(x) \wedge q(x)}=$ $|u|_{p(x)}+|u|_{q(x)}$. On the space $\left(L^{p(x)}(\Omega)\right)^{2}:=L^{p(x)}(\Omega) \times L^{p(x)}(\Omega)$, we define the norm $|(u, v)|_{p(x)}=\inf \left\{\lambda>0: \int_{\Omega}\left(|u|^{p(x)}+|v|^{p(x)}\right) / \lambda^{p(x)} \mathrm{d} x \leq 1\right\}$. On the space $\left(L^{p(x)}(\Omega)\right)^{2} \cap\left(L^{q(x)}(\Omega)\right)^{2}$, we define the norm $|(u, v)|_{p(x) \wedge q(x)}=|(u, v)|_{p(x)}+|(u, v)|_{q(x)}$. On the space $L^{p(x)}(\Omega)+L^{q(x)}(\Omega)$, we define the norm $|u|_{p(x) \vee q(x)}=\inf \left\{|v|_{p(x)}+|w|_{q(x)}\right.$ : $\left.v \in L^{p(x)}(\Omega), w \in L^{p(x)}(\Omega), u=v+w\right\}$.

Similar to Proposition 2.8, we have the following proposition.
Proposition 2.13 (1) Assume $1 \leq p(x), r(x)<\infty, f \in C\left(\Omega \times \mathbb{R}^{2}\right)$ and

$$
f(x, s, t) \leq c_{1}\left(\left|s^{\frac{p(x)}{r(x)}}+|t|^{\frac{p(x)}{r(x)}}\right) .\right.
$$

Then for every $(u, v) \in\left(L^{p(x)}(\Omega)\right)^{2}, f(\cdot, u, v) \in L^{r(x)}(\Omega)$ and the operator

$$
T_{1}:\left(L^{p(x)}(\Omega)\right)^{2} \rightarrow L^{r(x)}(\Omega):(u, v) \mapsto f(x, u, v)
$$

is continuous.
(2) Assume $1 \leq p(x), r(x), q(x), s(x)<\infty, f \in C\left(\Omega \times \mathbb{R}^{2}\right)$ and

$$
f(x, s, t) \leq c_{2}\left(|s|^{\frac{p(x)}{r(x)}}+|t|^{\frac{p(x)}{r(x)}}\right)+c_{3}\left(\left|s s^{\frac{q(x)}{s(x)}}+|t|^{\frac{q(x)}{s(x)}}\right) .\right.
$$

Then for every $(u, v) \in\left(L^{p(x)}(\Omega)\right)^{2} \cap\left(L^{q(x)}(\Omega)\right)^{2}, f(\cdot, u, v) \in L^{r(x)}(\Omega)+L^{s(x)}(\Omega)$ and the operator

$$
T_{2}:\left(L^{p(x)}(\Omega)\right)^{2} \cap\left(L^{q(x)}(\Omega)\right)^{2} \rightarrow L^{r(x)}(\Omega)+L^{s(x)}(\Omega):(u, v) \mapsto f(x, u, v)
$$

is continuous.
Now we display some basic properties of $p(x)$-Laplacian operators. Let $X$ be $W_{0}^{1, p(x)}(\Omega)$ or $W^{1, p(x)}\left(\mathbb{R}^{N}\right)$. Consider the following two functionals:

$$
\begin{gathered}
J_{1}(u)=\int_{\Omega} \frac{1}{p(x)}|\nabla u|^{p(x)} \mathrm{d} x, \quad \text { for all } u \in X=W_{0}^{1, p(x)}(\Omega) ; \\
J_{2}(u)=\int_{\mathbb{R}^{N}} \frac{1}{p(x)}\left(|\nabla u|^{p(x)}+|u|^{p(x)}\right) \mathrm{d} x, \quad \text { for all } u \in X=W^{1, p(x)}\left(\mathbb{R}^{N}\right) .
\end{gathered}
$$

We know that $J_{1}, J_{2} \in C^{1}(X, \mathbb{R})$, and the $p(x)$-Laplacian operator is the derivative operator of $J_{1}$ in the weak sense. We denote $L=J_{1}^{\prime}: X \rightarrow X^{*}$ and $T=J_{2}^{\prime}$ : $X \rightarrow X^{*}$, then

$$
\begin{gather*}
\langle L u, \tilde{u}\rangle=\int_{\Omega}|\nabla u|^{p(x)-2} \nabla u \nabla \tilde{u} \mathrm{~d} x, \quad \text { for all } u, \tilde{u} \in X,  \tag{2.3}\\
\langle T u, \tilde{u}\rangle=\int_{\mathbb{R}^{N}}\left(|\nabla u|^{p(x)-2} \nabla u \nabla \tilde{u}+|u|^{p(x)-2} u \tilde{u}\right) \mathrm{d} x, \quad \text { for all } u, \tilde{u} \in X . \tag{2.4}
\end{gather*}
$$

Proposition 2.14 ([11, 8])
(1) $L, T: X \rightarrow X^{*}$ are two continuous, bounded and strictly monotone operators.
(2) $L, T: X \rightarrow X^{*}$ are two mappings of type $\left(S_{+}\right)$. Here a map $L$ is called of type $\left(S_{+}\right)$if we have the property that $u_{n} \rightharpoonup u$ in $X$ and $\lim \sup _{n \rightarrow \infty}\left\langle L\left(u_{n}\right)-L(u), u_{n}-\right.$ $u\rangle \leq 0$, then $u_{n} \rightarrow u$ in $X$.
(3) $L, T: X \rightarrow X^{*}$ are two homeomorphisms.

### 2.2 A limit index theory due to Li

In this section, we will recall a limit index theory developed by Li [18]. Suppose $Z$ is a $\mathscr{G}$-Banach space, where $\mathscr{G}$ is a topological group. For the definition of index $i$ we refer to [26] Definition 5.9.

Definition 2.15 An index $i$ is said to satisfy the d-dimension property if there is a positive integer $d$ such that

$$
i\left(V^{d k} \cap S_{1}\right)=k
$$

for all dk-dimensional subspaces $V^{d k} \in \Sigma:=\{A \subset Z: A$ is closed and $g A=$ A for all $g \in \mathscr{G}\}$ such that $V^{d k} \cap \operatorname{Fix} \mathscr{G}=\{0\}$, where $S_{1}$ is the unit sphere in $Z$.

Proposition 2.16 ([18] Lemma 2.3) Suppose $Z=W_{1} \oplus W_{2}$ and $\operatorname{dim} W_{1}=k d$, where $W_{j}$ is a $\mathscr{G}$-invariant subspace, $j=1,2$. Let $i$ be an index satisfying the $d$-dimension property. If $W_{1} \cap \operatorname{Fix} \mathscr{G}=\{0\}, A \in \Sigma$ and $i(A)>k$, then $A \cap W_{2} \neq \emptyset$.

Suppose $U$ and $V$ are $\mathscr{G}$-invariant closed subspaces of $Z$ such that $Z=U \oplus V$, where $V$ is infinite dimension and $V=\overline{\bigcup_{j=1}^{\infty} V_{j}}$. Here $V_{j}$ is a $d n_{j}$-dimensional $\mathscr{G}-$ invariant subspace of $V$, and $V_{1} \subset V_{2} \subset \ldots$ for $j=1,2, \ldots$ Let $Z_{j}=U \oplus V_{j}$, and let $A_{j}=A \cap Z_{j}$ for all $A \in \Sigma$.

Definition 2.17 ([18] Definition 2.4) Let $i$ be an index satisfying the d-dimension property. A limit index $i^{\infty}$ with respect to $\left\{Z_{j}\right\}$ induced by $i$ is a mapping

$$
i^{\infty}: \Sigma \rightarrow \mathbb{Z} \cup\{-\infty,+\infty\}
$$

given by

$$
i^{\infty}(A)=\limsup _{j \rightarrow \infty}\left(i\left(A_{j}\right)-n_{j}\right)
$$

Proposition 2.18 ([18] Proposition 2.5) Let $A, B \in \Sigma$. Then $i^{\infty}$ satisfies:
(1) $A=\emptyset \Longleftrightarrow i^{\infty}(A)=-\infty$;
(2) (Monotonicity) $A \subset B \Rightarrow i^{\infty}(A) \leq i^{\infty}(B)$;
(3) (Subadditivity) $i^{\infty}(A \cup B) \leq i^{\infty}(A)+i(B)$;
(4) If $V \cap$ Fix $\mathscr{G}=\{0\}$, then $i^{\infty}\left(S_{\rho} \cap V\right)=0$, where $S_{\rho}=\{z \in Z,\|z\|=\rho\}$;
(5) If $Y_{0}$ and $\tilde{Y}_{0}$ are $\mathscr{G}$-invariant closed subspaces of $V$ such that $V=Y_{0} \oplus \tilde{Y}_{0}$, $\tilde{Y}_{0} \subset V_{j_{0}}$ for some $j_{0}$ and $\operatorname{dim} \tilde{Y}_{0}=d m$, then $i^{\infty}\left(S_{\rho} \cap Y_{0}\right) \geq-m$.

Definition 2.19 Let $Z$ be a Banach space which has a decomposition $Z=\overline{\cup_{j=1}^{\infty} Z_{j}}$ where $Z_{1} \subset Z_{2} \cdots, \operatorname{dim} Z_{j}=d n_{j}$. A functional $f \in C^{1}(Z, \mathbb{R})$ is said to satisfy the $(P S)_{c}^{*}$ condition with respect to $\left\{Z_{n}\right\}$ at the level $c \in \mathbb{R}$ if any sequence $\left\{z_{n_{k}}\right\}$, $z_{n_{k}} \in Z_{n_{k}}$ such that

$$
f\left(z_{n_{k}}\right) \rightarrow c \text { and }\left\|\left(f_{n_{k}}\right)^{\prime}\left(z_{n_{k}}\right)\right\| \rightarrow 0 \text { as } n_{k} \rightarrow \infty
$$

possesses a subsequence which converges in $Z$ to a critical point of $f$, where $f_{n_{k}}:=$ $\left.f\right|_{Z_{n_{k}}}$.

Theorem 2.20 (18] Corollary 4.4, [16] Theorem 2.7) Assume that (B1) $f \in C^{1}(Z, \mathbb{R})$ is $\mathscr{G}$-invariant;
(B2) there are $\mathscr{G}$-invariant closed subspaces $U$ and $V$ such that $V$ is infinite dimension and

$$
Z=U \oplus V
$$

(B3) there is a sequence of $\mathscr{G}$-invariant finite-dimensional subspaces

$$
V_{1} \subset V_{2} \cdots \subset V_{j} \subset \cdots, \operatorname{dim} V_{j}=d n_{j}
$$

such that $V=\overline{\cup_{j=1}^{\infty} V_{j}}$;
(B4) there is an index $i$ on $Z$ satisfying the d-dimension property;
(B5) there are $\mathscr{G}$-invariant subspaces $Y_{0}, \tilde{Y}_{0}, Y_{1}$ of $V$ such that $V=Y_{0} \oplus \tilde{Y}_{0}, Y_{1}$, $\tilde{Y}_{0} \subset V_{j_{0}}$ for some
$j_{0}$ and $\operatorname{dim} \tilde{Y}_{0}=d m \leq d k=\operatorname{dim} Y_{1}$;
(B6) there are $\alpha$ and $\beta, \alpha<\beta$ such that $f$ satisfies $(P S)_{c}^{*}$ with respect to $Z_{n}:=$ $U \oplus V_{n}$,
for all $c \in[\alpha, \beta]$;
(B7)

$$
\left\{\begin{array}{l}
(a) \quad \text { either } \operatorname{Fix} \mathscr{G} \subset U \oplus Y_{1} \text { or } \operatorname{Fix} \mathscr{G} \cap V=\{0\}, \\
(b) \quad \text { there is } \rho>0 \text { such that } f(z) \geq \alpha, \quad \text { for all } z \in Y_{0} \cap S_{\rho}, \\
(c) \quad f(z) \leq \beta, \quad \text { for all } z \in U \oplus Y_{1} .
\end{array}\right.
$$

If $i^{\infty}$ is the limit index induced by $i$, then the numbers

$$
d_{j}=\sup _{i^{\infty}(A) \geq j} \inf _{z \in A} f(z)
$$

are critical values of $f$ and $\alpha \leq d_{-m} \leq d_{-m-1} \leq \cdots \leq d_{-k+1} \leq \beta$. Moreover, if $d=$ $d_{l}=\cdots=d_{l+r}, r>0$, then $i\left(K_{c}\right) \geq r+1$, where $K_{c}=\left\{z \in Z ; f^{\prime}(z)=0, f(z)=d\right\}$.

Proof. By Proposition 2.18(5), $i^{\infty}\left(S_{\rho} \cap Y_{0}\right) \geq-m$ thus $\alpha \leq d_{-m}$. It is obvious that $d_{-m} \leq d_{-m-1} \leq \cdots \leq d_{-k+1}$. Let us turn to prove $d_{-k+1} \leq \beta$. Let $V_{j} \ominus Y_{1}$ be a fixed $\mathscr{G}$-invariant complementary subspace of $Y_{1}$ in $V_{j}, j \geq j_{0}$. It is easy to obtain that $\left(V_{j} \ominus Y_{1}\right) \cap \operatorname{Fix} \mathscr{G}=\{0\}$ since of (B7)(a). Suppose $A \in \Sigma$ and $i^{\infty}(A) \geq-k+1$, there must be some $j$ such that $i\left(A_{j}\right)-n_{j}>-k$, that is $i\left(A_{j}\right)>n_{j}-k$. On the other hand, we have $\operatorname{dim}\left(V_{j} \ominus Y_{1}\right)=d\left(n_{j}-k\right)$. By Proposition 2.16 we get $A_{j} \cap\left(U \oplus Y_{1}\right) \neq \emptyset$. Then $A \cap\left(U \oplus Y_{1}\right) \neq \emptyset$. By the definition of $d_{-k+1}$ and (B7)(c), we get $d_{-k+1} \leq \beta$. The proof that $d_{j}$ are critical values of $f$ is the Theorem 4.1 in [18].

Remark 2.21 In [18] Corollary 4.4 and [16] Theorem 2.7, this theorem is stated incorrectly, but the proof they gave there is essentially correct.

## 3 The bounded case

In this section, we always assume that (P1) is satisfied. Denote by $X$ the space $W_{0}^{1, p(x)}(\Omega)$ with the norm $\|u\|=|\nabla u|_{p(x)}$ as in Remark 2.5. The integral functional of (1.1) is

$$
\Phi(u, v)=-\int_{\Omega} \frac{1}{p(x)}|\nabla u|^{p(x)} \mathrm{d} x+\int_{\Omega} \frac{1}{p(x)}|\nabla v|^{p(x)} \mathrm{d} x-\mathcal{F}(u, v)
$$

where

$$
\mathcal{F}(u, v):=\int_{\Omega} F(x, u, v) \mathrm{d} x, \quad u, v \in X
$$

Definition 3.1 The pair $(u, v) \in X \times X$ is called a weak solution of (1.1) if

$$
\begin{align*}
& -\int_{\Omega}|\nabla u|^{p(x)-2} \nabla u \nabla \tilde{u} \mathrm{~d} x+\int_{\Omega}|\nabla v|^{p(x)-2} \nabla v \nabla \tilde{v} \mathrm{~d} x \\
= & \int_{\Omega} F_{s}(x, u, v) \tilde{u} \mathrm{~d} x+\int_{\Omega} F_{t}(x, u, v) \tilde{v} \mathrm{~d} x, \quad \text { for all }(\tilde{u}, \tilde{v}) \in X \times X . \tag{3.1}
\end{align*}
$$

For simplicity, using the operator $L$ defined in (2.3), we rewrite (3.1) as

$$
\langle(-L u, L v),(\tilde{u}, \tilde{v})\rangle=\left\langle\mathcal{F}^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle, \quad \text { for all }(\tilde{u}, \tilde{v}) \in X \times X
$$

where

$$
\langle(-L u, L v),(\tilde{u}, \tilde{v})\rangle:=\langle-L u, \tilde{u}\rangle+\langle L v, \tilde{v}\rangle,
$$

and

$$
\left\langle\mathcal{F}^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle:=\int_{\Omega} F_{s}(x, u, v) \tilde{u} \mathrm{~d} x+\int_{\Omega} F_{t}(x, u, v) \tilde{v} \mathrm{~d} x
$$

Lemma 3.2 Suppose $F$ satisfies (F1) and (F2), then
(1) $\Phi, \mathcal{F} \in C^{1}(X \times X, \mathbb{R})$ and

$$
\begin{equation*}
\left\langle\Phi^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle=\langle(-L u, L v),(\tilde{u}, \tilde{v})\rangle-\left\langle\mathcal{F}^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle . \tag{3.2}
\end{equation*}
$$

In particular, each critical point of $\Phi$ is a weak solution of (1.1).
(2) $\mathcal{F}^{\prime}: X \times X \rightarrow X^{*} \times X^{*}$ is completely continuous.

Proof . The proof of (1) is routine. The proof of (2) relies on Proposition 2.10 and we omit it.

As X is a separable and reflexive Banach space, there exist $\left\{e_{j}\right\}_{j=1}^{\infty} \subset X$ and $\left\{f_{i}\right\}_{i=1}^{\infty} \subset X^{*}$ such that

$$
X=\overline{\operatorname{span}\left\{e_{j} \mid j=1,2, \cdots\right\}}, \quad X^{*}=\overline{\operatorname{span}\left\{f_{i} \mid i=1,2, \cdots\right\}^{W^{*}}}, \text { and }\left\langle f_{i}, e_{j}\right\rangle=\delta_{i j} .
$$

For convenience, we write $X_{n}=\operatorname{span}\left\{e_{1}, \cdots, e_{n}\right\}, X_{n}^{\perp}=\overline{\operatorname{span}\left\{e_{n+1}, \cdots\right\}}$. Now set $E=X \times X, E_{n}=X_{n} \times X_{n}$. Define a group of $\mathscr{G}=\{\iota, \tau\} \cong \mathbb{Z}_{2}$ by setting

$$
\begin{equation*}
\tau(u, v)=(-u,-v), \iota(u, v)=(u, v) . \tag{3.3}
\end{equation*}
$$

Let

$$
\begin{equation*}
\Sigma=\{A \subset E: A \text { is closed and }(u, v) \in A \Rightarrow(-u,-v) \in A\} . \tag{3.4}
\end{equation*}
$$

An index $\gamma$ on $\Sigma$ is defined by
$\gamma(A)=\left\{\begin{array}{l}0 \text { if } A=\emptyset, \\ \min \left\{m \in \mathbb{Z}_{+}: \exists h \in C\left(A, \mathbb{R}^{m} \backslash\{0\}\right) \text { such that } h(-u,-v)=-h(u, v)\right\}, \\ +\infty \text { if such } h \text { dose not exist. }\end{array}\right.$
Then $\gamma$ is an index satisfying 1-dimension property by Borsuk-Ulam Theorem (see [26] Proposition II 5.2.). We can obtain a limit index $\gamma^{\infty}$ with respect to $\left\{E_{n}\right\}$ from $\gamma$.

Lemma 3.3 Assume that $F$ satisfies (F1) and (F2). Then any bounded sequence $\left\{\left(u_{n_{k}}, v_{n_{k}}\right)\right\}$ such that

$$
\begin{equation*}
\left(u_{n_{k}}, v_{n_{k}}\right) \in E_{n_{k}}, \Phi\left(u_{n_{k}}, v_{n_{k}}\right) \rightarrow c,\left\|\left(\Phi_{n_{k}}\right)^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right)\right\| \rightarrow 0 \text { as } n_{k} \rightarrow \infty \tag{3.6}
\end{equation*}
$$

possesses a subsequence which converges in $E$ to a critical point of $\Phi$, where $\Phi_{n_{k}}:=$ $\left.\Phi\right|_{E_{n_{k}}}$.

Proof . Since $E$ is reflexive, going if necessary to a subsequence, we can assume that $u_{n_{k}} \rightharpoonup u$ and $v_{n_{k}} \rightharpoonup v$. Observing that $E=\overline{\cup_{n=1}^{\infty} E_{n}}$, we can choose $\left(\bar{u}_{n_{k}}, \bar{v}_{n_{k}}\right) \in E_{n_{k}}$ such that $\bar{u}_{n_{k}} \rightarrow u$ and $\bar{v}_{n_{k}} \rightarrow v$. Hence

$$
\begin{align*}
& \lim _{n_{k} \rightarrow \infty}\left\langle\Phi^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(u_{n_{k}}-u, 0\right)\right\rangle \\
= & \lim _{n_{k} \rightarrow \infty}\left\langle\Phi^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(u_{n_{k}}-\bar{u}_{n_{k}}, 0\right)\right\rangle+\lim _{n_{k} \rightarrow \infty}\left\langle\Phi^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(\bar{u}_{n_{k}}-u, 0\right)\right\rangle \\
= & \lim _{n_{k} \rightarrow \infty}\left\langle\left(\Phi_{n_{k}}\right)^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(u_{n_{k}}-\bar{u}_{n_{k}}, 0\right)\right\rangle=0 . \tag{3.7}
\end{align*}
$$

Substituting (3.2) into (3.7) and noticing that $\mathcal{F}^{\prime}$ is completely continuous, we obtain

$$
\begin{equation*}
\lim _{n_{k} \rightarrow \infty}\left\langle L u_{n_{k}}, u_{n_{k}}-u\right\rangle=0 \tag{3.8}
\end{equation*}
$$

By computing the limit of $\left\langle\Phi^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(0, v_{n_{k}}-v\right)\right\rangle$ in the similar way using $\bar{v}_{n_{k}}$, we obtain

$$
\begin{equation*}
\lim _{n_{k} \rightarrow \infty}\left\langle L v_{n_{k}}, v_{n_{k}}-v\right\rangle=0 . \tag{3.9}
\end{equation*}
$$

From (3.8) and (3.9), we conclude that $u_{n_{k}} \rightarrow u$ and $v_{n_{k}} \rightarrow v$ since $L$ is of type $\left(S_{+}\right)$.
It remains to show that $(u, v)$ is a critical point of $\Phi$. Taking arbitrarily $\left(\bar{u}_{j}, \bar{v}_{j}\right) \in$ $E_{j}$, then for $n_{k} \geq j$ we have

$$
\begin{equation*}
\left\langle\Phi^{\prime}(u, v),\left(\bar{u}_{j}, \bar{v}_{j}\right)\right\rangle=\left\langle\Phi^{\prime}(u, v)-\Phi^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(\bar{u}_{j}, \bar{v}_{j}\right)\right\rangle+\left\langle\left(\Phi_{n_{k}}\right)^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(\bar{u}_{j}, \bar{v}_{j}\right)\right\rangle . \tag{3.10}
\end{equation*}
$$

Taking $n_{k} \rightarrow \infty$ in the right side of (3.10), we obtain $\left\langle\Phi^{\prime}(u, v),\left(\bar{u}_{j}, \bar{v}_{j}\right)\right\rangle=0$. Hence $\Phi^{\prime}(u, v)=0$.

Lemma 3.4 Suppose that $F$ satisfies (F1)-(F4). Then the functional $\Phi$ satisfies $(P S)_{c}^{*}$ with respect to $\left\{E_{n}\right\}$ for each $c$.

Proof . By Lemma 3.3, we only need to prove that each sequence satisfying 3.6) is bounded. We can assume that $\left\|u_{n_{k}}\right\| \geq 1$ and $\left\|v_{n_{k}}\right\| \geq 1$. From Proposition 2.7 and (F4), we have

$$
\begin{align*}
\left\|u_{n_{k}}\right\| & \geq\left\langle-\left(\Phi_{n_{k}}\right)^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(u_{n_{k}}, 0\right)\right\rangle \\
& =\left\langle L u_{n_{k}}, u_{n_{k}}\right\rangle+\int_{\Omega} F_{s}\left(x, u_{n_{k}}, v_{n_{k}}\right) u_{n_{k}} \mathrm{~d} x \geq\left\|u_{n_{k}}\right\|^{p_{-}} \tag{3.11}
\end{align*}
$$

So $\left\|u_{n_{k}}\right\|$ is bounded. On the other hand, from (F3), Proposition 2.7 and Hölder inequality, we have

$$
\begin{align*}
c_{1} \geq & \Phi\left(u_{n_{k}}, v_{n_{k}}\right) \\
= & -\int_{\Omega} \frac{1}{p(x)}\left|\nabla u_{n_{k}}\right|^{p(x)} \mathrm{d} x+\int_{\Omega} \frac{1}{p(x)}\left|\nabla v_{n_{k}}\right|^{p(x)} \mathrm{d} x-\mathcal{F}\left(u_{n_{k}}, v_{n_{k}}\right) \\
\geq & -\int_{\Omega} \frac{1}{p(x)}\left|\nabla u_{n_{k}}\right|^{p(x)} \mathrm{d} x+\int_{\Omega} \frac{1}{p(x)}\left|\nabla v_{n_{k}}\right|^{p(x)} \mathrm{d} x \\
& -\frac{1}{\mu} \int_{\Omega}\left(u_{n_{k}} F_{s}\left(x, u_{n_{k}}, v_{n_{k}}\right)+v_{n_{k}} F_{t}\left(x, u_{n_{k}}, v_{n_{k}}\right)\right) \mathrm{d} x \\
= & -\int_{\Omega} \frac{1}{p(x)}\left|\nabla u_{n_{k}}\right|^{p(x)} \mathrm{d} x+\int_{\Omega} \frac{1}{p(x)}\left|\nabla v_{n_{k}}\right|^{p(x)} \mathrm{d} x-\frac{1}{\mu}\left\langle\mathcal{F}^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(u_{n_{k}}, v_{n_{k}}\right)\right\rangle \\
= & -\int_{\Omega}\left(\frac{1}{p(x)}-\frac{1}{\mu}\right)\left|\nabla u_{n_{k}}\right|^{p(x)} \mathrm{d} x+\int_{\Omega}\left(\frac{1}{p(x)}-\frac{1}{\mu}\right)\left|\nabla v_{n_{k}}\right|^{p(x)} \mathrm{d} x \\
& +\frac{1}{\mu}\left\langle\left(\Phi_{n_{k}}\right)^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(u_{n_{k}}, v_{n_{k}}\right)\right\rangle \\
\geq & -\left(\frac{1}{p_{-}}-\frac{1}{\mu}\right)\left\|u_{n_{k}}\right\|^{p_{+}}+\left(\frac{1}{p_{+}}-\frac{1}{\mu}\right)\left\|v_{n_{k}}\right\|^{p_{-}} \\
& -\frac{2}{\mu}\left\|\left(\Phi_{n_{k}}\right)^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right)\right\|\left(\left\|u_{n_{k}}\right\|+\left\|v_{n_{k}}\right\|\right) . \tag{3.12}
\end{align*}
$$

So $\left\|v_{n_{k}}\right\|$ is bounded. Thus $\left\{\left(u_{n_{k}}, v_{n_{k}}\right)\right\}$ is a bounded sequence in $E$.

Proposition 3.5 ([8] Lemma 3.3) Assume that $X=\overline{\operatorname{span}\left\{e_{j} \mid j=1,2, \cdots\right\}, X_{m}^{\perp}=}$ $\overline{\operatorname{span}\left\{e_{m+1}, \cdots\right\}}, f: X \rightarrow \mathbb{R}$ is a weakly-strongly continuous and $f(0)=0$. Then

$$
\delta_{m}:=\sup _{u \in X_{m}^{\perp},\|u\|=1}|f(u)| \rightarrow 0 \text {, as } m \rightarrow \infty
$$

Proof of Theorem 1.1. Note that $\Phi$ is invariant with respect to the action of $\mathscr{G}$. We shall verify that $\Phi$ satisfies the hypotheses of Theorem 2.20. Set $E=U \oplus V$, where $U=X \times\{0\}$ and $V=\{0\} \times X$. Set $Y_{0}=\{0\} \times X_{m}^{\perp}$ and $Y_{1}=\{0\} \times X_{k}$ where $m$ and $k$ are to be determined. Then $Y_{0}$ and $Y_{1}$ are $\mathscr{G}$-invariant and $\operatorname{codim}_{V} Y_{0}=m$, $\operatorname{dim} Y_{1}=k$, $\operatorname{Fix} \mathscr{G}=\{(0,0)\}$. So $\operatorname{Fix} \mathscr{G} \cap V=\{(0,0)\}$ and (B7)(a) of Theorem 2.20 is satisfied. It remains to verify (b) and (c) of (B7).

First, we verify (b) of (B7). By (F3), we have

$$
\Phi(u, 0)=-\int_{\Omega} \frac{1}{p(x)}|\nabla u|^{p(x)} \mathrm{d} x-\mathcal{F}(u, 0) \leq-\frac{1}{p_{+}} \int_{\Omega}|\nabla u|^{p(x)} \mathrm{d} x-c_{1} \int_{\Omega}|u|^{\mu} \mathrm{d} x+c_{2} .
$$

Therefore $\sup _{u \in X} \Phi(u, 0)<+\infty$. Choose $\alpha$ such that $\alpha>\sup _{u \in X} \Phi(u, 0)$.
If $(0, v) \in Y_{0} \cap S_{\rho}$ (where $\rho>1$ is to be determined), we have $v \in X_{m}^{\perp}$ and $\|v\|=\rho$. Define $f: X \rightarrow \mathbb{R}, f(v)=|v|_{r(x)}$. Since the embedding $X \hookrightarrow L^{r(x)}(\Omega)$ is compact by Proposition 2.10, $f$ is weakly-strongly continuous. By Proposition 3.5, we have $\delta_{m} \rightarrow 0$ as $m \rightarrow \infty$. By (F2) we obtain

$$
\begin{aligned}
\Phi(0, v) & =\int_{\Omega} \frac{1}{p(x)}|\nabla v|^{p(x)} \mathrm{d} x-\mathcal{F}(0, v) \\
& \geq \frac{1}{p_{+}} \int_{\Omega}|\nabla v|^{p(x)} \mathrm{d} x-c_{3} \int_{\Omega}|v|^{r(x)} \mathrm{d} x-c_{4} \\
& \geq \frac{1}{p_{+}}\|v\|^{p_{-}}-c_{3}|v|_{r(x)}^{r_{+}}-c_{4} \\
& \geq \frac{1}{p_{+}} \rho^{p_{-}}-c_{3} \delta_{m}^{r_{+}} \rho^{r_{+}}-c_{4} .
\end{aligned}
$$

Setting $\rho=\left(\frac{c_{3} p_{+} r_{+} \delta_{m}^{r}+}{p_{-}}\right)^{\frac{1}{p_{-}-r_{+}}}$, we have

$$
\left.\Phi\right|_{Y_{0} \cap S_{\rho}} \geq\left(r_{+}-p_{-}\right)\left(p_{+} r_{+}\right)^{\frac{r_{+}}{p_{-}-r_{+}}}\left(\frac{c_{3}}{p_{-}}\right)^{\frac{p_{-}}{p_{-}-r_{+}}} \delta_{m}^{\frac{p_{-}-r_{+}}{p_{-}}}-c_{4} \rightarrow+\infty \text { as } m \rightarrow \infty .
$$

Next, we verify (c) of (B7). For each $(u, v) \in U \oplus Y_{1}$ and $\|u\|>1,\|v\|>1$,

$$
\begin{aligned}
\Phi(u, v) & \leq-\frac{1}{p_{+}}\|u\|^{p_{-}}+\frac{1}{p_{-}}\|v\|^{p_{+}}-c_{5} \int_{\Omega}\left(|u|^{\mu}+|v|^{\mu}\right) \mathrm{d} x+c_{6} \\
& \leq \frac{1}{p_{-}}\|v\|^{p_{+}}-c_{5} \int_{\Omega}|v|^{\mu} \mathrm{d} x+c_{6} .
\end{aligned}
$$

Since all norms are equivalent in the finite dimension space $Y_{1}$, we get

$$
\Phi(u, v) \leq \frac{1}{p_{-}}\|v\|^{p_{+}-c_{7}}\|v\|^{\mu}+c_{8}
$$

Then we have $\left.\sup \Phi\right|_{U \oplus Y_{1}}<+\infty$ since $\mu>p_{+}$. Thus we can choose $k>m$ and $\beta>\alpha$ such that $\left.\Phi\right|_{U \oplus Y_{1}} \leq \beta$.

So

$$
d_{j}=\sup _{\gamma^{\infty}(A) \geq j} \inf _{z \in A} \Phi(z), \quad-k+1 \leq j \leq-m,
$$

are critical values of $\Phi$ and $\alpha \leq d_{j} \leq \beta$. Since $\alpha$ can be chosen arbitrarily large, $\Phi$ has a sequence of critical values $d_{n} \rightarrow+\infty$.

## 4 The $\mathbb{R}^{N}$ case

In this section, we always assume that (P2) is satisfied and denote $X$ by $W^{1, p(x)}\left(\mathbb{R}^{N}\right)$ with the norm $\|u\|$ defined by 2.2 and denote $X_{r}$ by $W_{r}^{1, p(x)}\left(\mathbb{R}^{N}\right)$ with the same norm. The integral functional of (1.2) is
$\Psi(u, v)=-\int_{\mathbb{R}^{N}} \frac{1}{p(x)}\left(|\nabla u|^{p(x)}+|u|^{p(x)}\right) \mathrm{d} x+\int_{\mathbb{R}^{N}} \frac{1}{p(x)}\left(|\nabla v|^{p(x)}+|v|^{p(x)}\right) \mathrm{d} x-\mathcal{G}(u, v)$, where

$$
\mathcal{G}(u, v):=\int_{\mathbb{R}^{N}} G(|x|, u, v) \mathrm{d} x, \quad u, v \in X
$$

Definition $4.1(u, v) \in X \times X$ is called a weak solution of (1.2) if

$$
\begin{gather*}
-\int_{\mathbb{R}^{N}}\left(|\nabla u|^{p(x)-2} \nabla u \nabla \tilde{u}+|u|^{p(x)-2} u \tilde{u}\right) \mathrm{d} x \\
\\
+\int_{\mathbb{R}^{N}}\left(|\nabla v|^{p(x)-2} \nabla v \nabla \tilde{v}+|v|^{p(x)-2} v \tilde{v}\right) \mathrm{d} x  \tag{4.1}\\
= \\
\int_{\mathbb{R}^{N}} G_{s}(|x|, u, v) \tilde{u} \mathrm{~d} x+\int_{\mathbb{R}^{N}} G_{t}(|x|, u, v) \tilde{v} \mathrm{~d} x,
\end{gather*}
$$

for all $(\tilde{u}, \tilde{v}) \in X \times X$.
Denote

$$
\langle(T u, T v),(\tilde{u}, \tilde{v})\rangle:=\langle T u, \tilde{u}\rangle+\langle T v, \tilde{v}\rangle
$$

where $T$ is defined as 2.4 and denote

$$
\left\langle\mathcal{G}^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle:=\int_{\mathbb{R}^{N}} G_{s}(|x|, u, v) \tilde{u} \mathrm{~d} x+\int_{\mathbb{R}^{N}} G_{t}(|x|, u, v) \tilde{v} \mathrm{~d} x
$$

Then (4.1) can be rewritten as

$$
\langle(-T u, T v),(\tilde{u}, \tilde{v})\rangle=\left\langle\mathcal{G}^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle, \quad \text { for all }(\tilde{u}, \tilde{v}) \in X \times X
$$

Proposition 4.2 ([22] Principle of symmetric criticality) If $u$ is a critical point of $\left.\Psi\right|_{X_{r} \times X_{r}}$, then $u$ is also a critical point of $\left.\Psi\right|_{X \times X}$ and thus a radially symmetric solution of problem (1.2).

By the principle of symmetric criticality, to solve problem (1.2), we shall to find the critical points of $\Psi$ restricted on $X_{r} \times X_{r}$ using the limit index theory.

Lemma 4.3 Suppose G satisfies (G1)-(G4). Then
(1) $\Psi, \mathcal{G} \in C^{1}\left(X_{r} \times X_{r}, \mathbb{R}\right)$ and
$\left\langle\Psi^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle=\langle(-T u, T v),(\tilde{u}, \tilde{v})\rangle-\left\langle\mathcal{G}^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle, \quad$ for all $(\tilde{u}, \tilde{v}) \in X_{r} \times X_{r}$.
In particular, each critical point of $\Psi$ is a weak solution of the problem (1.2). (2) $\mathcal{G}^{\prime}: X_{r} \times X_{r} \rightarrow X_{r}^{*} \times X_{r}^{*}$ is completely continuous.

Proof . (1) is obvious. Now we shall prove $\mathcal{G}^{\prime}$ is continuous. Suppose $\left(u_{n}, v_{n}\right) \rightarrow$ $(u, v) \in X_{r} \times X_{r}$. By Proposition 2.9, we have $\left(u_{n}, v_{n}\right) \rightarrow(u, v) \in\left(L^{p(x)}\left(\mathbb{R}^{N}\right)\right)^{2} \cap$ $\left(L^{q(x)}\left(\mathbb{R}^{N}\right)\right)^{2}$. It follows from (G2) and Proposition 2.13(2) that

$$
\begin{aligned}
& G_{s}\left(|x|, u_{n}, v_{n}\right) \rightarrow G_{s}(|x|, u, v) \text { in } L^{p^{o}(x)}\left(\mathbb{R}^{N}\right)+L^{q^{o}(x)}\left(\mathbb{R}^{N}\right), \\
& G_{t}\left(|x|, u_{n}, v_{n}\right) \rightarrow G_{t}(|x|, u, v) \text { in } L^{p^{o}(x)}\left(\mathbb{R}^{N}\right)+L^{q^{o}(x)}\left(\mathbb{R}^{N}\right) .
\end{aligned}
$$

For all $(\tilde{u}, \tilde{v}) \in X_{r} \times X_{r}$, we obtain, by Hölder inequality (2.1),

$$
\begin{aligned}
& \left|\left\langle\mathcal{G}^{\prime}\left(u_{n}, v_{n}\right),(\tilde{u}, \tilde{v})\right\rangle-\left\langle\mathcal{G}^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle\right| \\
\leq & \int_{\mathbb{R}^{N}}\left|G_{s}\left(|x|, u_{n}, v_{n}\right)-G_{s}(|x|, u, v)\right||\tilde{u}| \mathrm{d} x \\
& +\int_{\mathbb{R}^{N}}\left|G_{t}\left(|x|, u_{n}, v_{n}\right)-G_{t}(|x|, u, v)\right||\tilde{v}| \mathrm{d} x \\
\leq & 2\left|G_{s}\left(|x|, u_{n}, v_{n}\right)-G_{s}(|x|, u, v)\right|_{p^{o}(x) \vee q^{o}(x)}|\tilde{u}|_{p(x) \wedge q(x)} \\
& +2\left|G_{t}\left(|x|, u_{n}, v_{n}\right)-G_{t}(|x|, u, v)\right|_{p^{o}(x) \vee q^{o}(x)}|\tilde{v}|_{p(x) \wedge q(x)},
\end{aligned}
$$

where $1 / p(x)+1 / p^{o}(x)=1,1 / q(x)+1 / q^{o}(x)=1$. Thus

$$
\left\|\mathcal{G}^{\prime}\left(u_{n}, v_{n}\right)-\mathcal{G}^{\prime}(u, v)\right\|_{X_{r}^{*} \times X_{r}^{*}} \rightarrow 0
$$

as $n \rightarrow \infty$.
Now let us prove that $\mathcal{G}^{\prime}$ is completely continuous. For any $\varepsilon>0$, using (G2) and (G4), we obtain $C_{\varepsilon}>0$ such that

$$
\left|G_{s}(|x|, s, t)\right|+\left|G_{t}(|x|, s, t)\right| \leq \varepsilon\left(|s|^{p(x)-1}+|t|^{p(x)-1}\right)+C_{\varepsilon}\left(|s|^{q(x)-1}+|t|^{q(x)-1}\right) .
$$

Assume that $\left(u_{n}, v_{n}\right) \rightharpoonup(u, v)$ in $X_{r} \times X_{r}$. Since $X_{r} \hookrightarrow L^{q(x)}\left(\mathbb{R}^{N}\right)$ is compact by Proposition 2.11, we have $\left(u_{n}, v_{n}\right) \rightarrow(u, v)$ in $\left(L^{q(x)}\left(\mathbb{R}^{N}\right)\right)^{2}$. By Proposition 2.13(1) we have

$$
G_{s}\left(|x|, u_{n}, v_{n}\right)-\varepsilon\left(\left|u_{n}\right|^{p(x)-1}+\left|v_{n}\right|^{p(x)-1}\right) \rightarrow G_{s}(|x|, u, v)-\varepsilon\left(|u|^{p(x)-1}+|v|^{p(x)-1}\right)
$$

in $\left(L^{q^{o}(x)}\left(\mathbb{R}^{N}\right)\right)^{2}$, and

$$
G_{t}\left(|x|, u_{n}, v_{n}\right)-\varepsilon\left(\left|u_{n}\right|^{p(x)-1}+\left|v_{n}\right|^{p(x)-1}\right) \rightarrow G_{t}(|x|, u, v)-\varepsilon\left(|u|^{p(x)-1}+|v|^{p(x)-1}\right)
$$

in $\left(L^{q^{o}(x)}\left(\mathbb{R}^{N}\right)\right)^{2}$.
So we obtain

$$
\begin{aligned}
& \left\|G_{s}\left(|x|, u_{n}, v_{n}\right)-G_{s}(|x|, u, v)\right\|+\left\|G_{t}\left(|x|, u_{n}, v_{n}\right)-G_{t}(|x|, u, v)\right\| \\
= & \sup _{\|\tilde{u}\| \leq 1} \int_{\mathbb{R}^{N}}\left|G_{s}\left(|x|, u_{n}, v_{n}\right)-G_{s}(|x|, u, v) \| \tilde{u}\right| \mathrm{d} x \\
& +\sup _{\|\tilde{v}\| \leq 1} \int_{\mathbb{R}^{N}}\left|G_{t}\left(|x|, u_{n}, v_{n}\right)-G_{t}(|x|, u, v) \| \tilde{v}\right| \mathrm{d} x<c \varepsilon .
\end{aligned}
$$

Therefore $\mathcal{G}^{\prime}$ is completely continuous.
Since $X_{r}$ is a separable and reflexive Banach space, there exist $\left\{e_{j}\right\}_{j=1}^{\infty} \subset X_{r}$ such that $\left(X_{r}\right)_{n}:=\operatorname{span}\left\{e_{1}, \cdots, e_{n}\right\}$ and $\left(X_{r}\right)_{n}^{\perp}=\overline{\operatorname{span}\left\{e_{n+1}, \cdots\right\}}$. Now set $E=X_{r} \times X_{r}$ and $E_{n}=\left(X_{r}\right)_{n} \times\left(X_{r}\right)_{n}$. As we have done in (3.3), (3.4) and (3.5), we can obtain a limit index $\gamma^{\infty}$ with respect to $\left\{E_{n}\right\}$.

Lemma 4.4 Suppose that $G$ satisfied (G1)-(G5). Then $\Psi$ satisfies $(P S)_{c}^{*}$ condition with respect to $\left\{E_{n}\right\}$ for each $c$.

Proof . Lemma 3.3 is also suitable here if we replace $\Phi$ and $L$ by $\Psi$ and $T$ respectively. Thus we only need to prove each sequence satisfying

$$
\left\{\left(u_{n_{k}}, v_{n_{k}}\right)\right\} \in E_{n_{k}}, \Psi\left(u_{n_{k}}, v_{n_{k}}\right) \rightarrow c,\left\|\left(\Psi_{n_{k}}\right)^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right)\right\| \rightarrow 0 \text { as } n_{k} \rightarrow \infty,
$$

is bounded where $\Psi_{n_{k}}:=\left.\Psi\right|_{E_{n_{k}}}$. By (G5) and Proposition 2.7 similar to (3.11), we have

$$
\left\|u_{n_{k}}\right\| \geq\left\langle-\left(\Psi_{n_{k}}\right)^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right),\left(u_{n_{k}}, 0\right)\right\rangle \geq\left\|u_{n_{k}}\right\|^{p_{-}} .
$$

So $\left\|u_{n_{k}}\right\|$ is bounded in $X_{r}$. On the other hand, by (G3), similar to (3.12), we have

$$
\begin{aligned}
c_{1} \geq & -\left(\frac{1}{p_{-}}-\frac{1}{\mu}\right)\left\|u_{n_{k}}\right\|^{p_{+}}+\left(\frac{1}{p_{+}}-\frac{1}{\mu}\right)\left\|v_{n_{k}}\right\|^{p_{-}} \\
& -\frac{2}{\mu}\left\|\left(\Psi_{n_{k}}\right)^{\prime}\left(u_{n_{k}}, v_{n_{k}}\right)\right\|\left(\left\|u_{n_{k}}\right\|+\left\|v_{n_{k}}\right\|\right) .
\end{aligned}
$$

So $\left\|v_{n_{k}}\right\|$ is bounded in $X_{r}$. Thus $\left\{\left(u_{n_{k}}, v_{n_{k}}\right)\right\}$ is a bounded sequence in $E$.
Proof of Theorem 1.2. We shall find the critical points of $\Psi$ in $E$ by using Theorem 2.20. By the assumption (G6), $\Psi$ is invariant with respect to $\mathscr{G}$. Set $E=U \oplus V$, where $U=X_{r} \times\{0\}$ and $V=\{0\} \times X_{r}$. Set $Y_{0}=\{0\} \times\left(X_{r}\right)_{m}^{\perp}$ and $Y_{1}=\{0\} \times\left(X_{r}\right)_{k}$ where $m$ and $k$ are to be determined. Then $Y_{0}$ and $Y_{1}$ are $\mathscr{G}_{-}$ invariant and $\operatorname{codim}_{V} Y_{0}=m, \operatorname{dim} Y_{1}=k, \operatorname{Fix} \mathscr{G}=\{(0,0)\}$. So Fix $\mathscr{G} \cap V=\{(0,0)\}$ and (B7)(a) of Theorem 2.20 is satisfied. It remains to verify (b) and (c) of (B7).

First, we verify (b) of (B7). After integrating, we obtain from (G2)-(G4) the existence of two positive constants $c_{1}$ and $c_{2}<1 / p_{+}$such that

$$
G(|x|, s, 0) \geq c_{1}|s|^{\mu}-c_{2}|s|^{p(x)}, \quad \text { for all } x \in \mathbb{R}^{N}, s \in \mathbb{R} .
$$

Hence, for all $u \in X_{r}$, we have

$$
\begin{aligned}
\Psi(u, 0) & =-\int_{\mathbb{R}^{N}} \frac{1}{p(x)}\left(|\nabla u|^{p(x)}+|u|^{p(x)}\right) \mathrm{d} x-\mathcal{G}(u, 0) \\
& \leq-\int_{\mathbb{R}^{N}} \frac{1}{p(x)}\left(|\nabla u|^{p(x)}+|u|^{p(x)}\right) \mathrm{d} x-c_{1} \int_{\mathbb{R}^{N}}|u|^{\mu} \mathrm{d} x+c_{2} \int_{\mathbb{R}^{N}}|u|^{p(x)} \mathrm{d} x \\
& <\infty .
\end{aligned}
$$

Then we can choose $\alpha$ such that $\alpha>\sup _{u \in X_{r}} \Psi(u, 0)$.
If $(0, v) \in Y_{0} \cap S_{\rho}$ (where $\rho>1$ is to be determined), we have $v \in\left(X_{r}\right)_{m}^{\perp}$ and $\|v\|=\rho$. Define $f: X_{r} \rightarrow \mathbb{R}, f(v)=|v|_{q(x)}$. Since the compact embedding $X_{r} \hookrightarrow L^{q(x)}(\Omega), f$ is weakly-strongly continuous. By Proposition $3.5, \delta_{m} \rightarrow 0$ as $m \rightarrow \infty$. Then by (G2), (G3),

$$
\begin{aligned}
\Psi(0, v) & =\int_{\mathbb{R}^{N}} \frac{1}{p(x)}\left(|\nabla v|^{p(x)}+|v|^{p(x)}\right) \mathrm{d} x-\mathcal{G}(0, v) \\
& \geq \frac{1}{p_{+}} \int_{\mathbb{R}^{N}}\left(|\nabla v|^{p(x)}+|v|^{p(x)}\right) \mathrm{d} x-c_{3} \int_{\mathbb{R}^{N}}|v|^{q(x)} \mathrm{d} x-c_{4} \\
& \geq \frac{1}{p_{+}}\|v\|^{p_{-}}-c_{3}|v|_{q(x)}^{q_{+}}-c_{4} \\
& \geq \frac{1}{p_{+}} \rho^{p_{-}}-c_{3} \delta_{m}^{q_{+}} \rho^{q_{+}}-c_{4} .
\end{aligned}
$$

Setting $\rho=\left(\frac{c_{3} p_{+} q_{+} \delta_{m+}^{q_{+}}}{p_{-}}\right)^{\frac{1}{p_{-} q_{+}}}$, we have

$$
\left.\Psi\right|_{Y_{0} \cap S_{\rho}} \geq\left(q_{+}-p_{-}\right)\left(p_{+} q_{+}\right)^{\frac{q_{+}}{p_{-}-q_{+}}}\left(\frac{c_{3}}{p_{-}}\right)^{\frac{p_{-}}{p_{-}-q_{+}}} \delta_{m}^{\frac{p_{-}-q_{+}}{p_{-}-q_{+}}}-c_{4} \rightarrow+\infty \text { as } m \rightarrow \infty .
$$

Next, we verify (c) of (B7). For each $(u, v) \in U \oplus Y_{1}$, and $\|u\|>1,\|v\|>1$,

$$
\begin{aligned}
\Psi(u, v) & \leq-\frac{1}{p_{+}}\|u\|^{p_{-}}+\frac{1}{p_{-}}\|v\|^{p_{+}}-c_{5} \int_{\Omega}\left(|u|^{\mu}+|v|^{\mu}\right) \mathrm{d} x+c_{6} \\
& \leq \frac{1}{p_{-}}\|v\|^{p_{+}}-c_{5} \int_{\Omega}|v|^{\mu} \mathrm{d} x+c_{6}
\end{aligned}
$$

Since all norms are equivalent in the finite dimension space $Y_{1}$, we get

$$
\Psi(u, v) \leq \frac{1}{p_{-}}\|v\|^{p_{+}-c_{7}}\|v\|^{\mu}+c_{8}
$$

Then we have $\left.\sup \Psi\right|_{U \oplus Y_{1}}<+\infty$ since $\mu>p_{+}$. Thus we can choose $k>m$ and $\beta>\alpha$ such that $\left.\Psi\right|_{U \oplus Y_{1}} \leq \beta$.

So

$$
d_{j}=\sup _{\gamma^{\infty}(A) \geq j} \inf _{z \in A} \Psi(z), \quad-k+1 \leq j \leq-m
$$

are critical values of $\Psi$ and $\alpha \leq d_{j} \leq \beta$. Since $\alpha$ can be chosen arbitrarily large, $\Psi$ has a sequence of critical values $d_{n} \rightarrow+\infty$.

If $N=4$ or $N \geq 6$, using the Bartsch-Willem's famous nonradial solutions result in [2] (see also [27] Theorem 1.31), the problem (1.2) possesses infinitely many nonradial solutions.

## Acknowledgement.

The author would like to thank Professor Xian-Ling Fan for his valuable suggestions and comments.

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[^0]:    *Project supported by National Natural Science Foundation of China (10671084)
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